RoboMaster Snail

2305 Brushless DC Motor

User Guide

V1.0 2019.10





Disclaimer

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Warning

- 1. Use the motor in a safe environment. To avoid injury, DO NOT approach or touch the motor while it is in operation.
- 2. Make sure all parts of the motor are in good condition. Replace any worn or damaged parts when necessary.
- 3. Make sure all cables are properly connected before use.
- 4. Make sure the motor is securely mounted before use.
- 5. When used with other electronic speed controllers without the self-protection function, make sure the motor is not stalled for an extended period; otherwise, the motor may be damaged.
- 6. DO NOT allow any foreign materials to come into contact with the rotors, as this may negatively affect performance.
- 7. The temperature of the motor increases when the output power is high. Handle carefully to avoid scalding.

Introduction

The RoboMaster Snail 2305 is a sensorless external rotor brushless DC motor. The 2305 motor boosts high speed, low noise, excellent heat dissipation, and high power density, and can be used in fields such as multirotor aircraft flights, robotic competitions, and educational research. The high dynamic response and outstanding transmission efficiency of the 2305 motor make it an optimal solution for situations that require high rotational speed, low torque, and direct driving. The 2305 motor has gone through rigorous impact simulation and drop testing to ensure structural strength and reliability.

In the Box



Mounting the Motor

Refer to the dimensions below to mount the motor to an appropriate platform.



Note: Pay attention to the size and the depth of the mounting holes. Use appropriately-sized screws to mount the motor properly according to the depth of the mounting holes and the platform where the motor will be mounted. DO NOT allow any foreign materials to come into contact with the mounting holes on the bottom of the motor when mounting and detaching the motor.

2305 Motor Performance

The following data was generated using the 2305 motor with a RoboMaster C615 Brushless DC Motor Speed Controller.



η - Motor Efficiency, T- Torque, P- Output Power, I- Speed Controller Input Current, n- Rotational Speed

The data above was generated in a laboratory setting with an input voltage of 24 V, at the temperature of 25° C (77° F). These figures should be used for reference only. Make sure to control running time properly in accordance with actual working temperature and dissipation.

Specifications

Dimensions	Outer diameter of motor: Ø29 mm Total height: 28.2 mm Output shaft diameter: Ø2.95 mm
Weight (without cable)	27.8 g
Rated Voltage	DC 24 V
Pole Pairs	7
Stator Size	23×5 mm
Rotational Speed without Load	21000 rpm
No Load Current	0.4 A
Speed Constant	875 rpm/V
Torque Constant	10.9 mN·m/A
Counter-Electromotive Force Constant	0.0012 V/rpm
Mechanical Time Constant	150 ms
Rotor Rotational Inertia	1.84 kg·mm ²
Phase Inductance	25.9 µH
Phase Resistance	181.5 mΩ

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